

# Data Analytics for Solar PV: Case Studies in EL Imaging and Re-Analysis of Field Data

**Xin Chen, Baojie Li, Anubhav Jain (LBNL)**

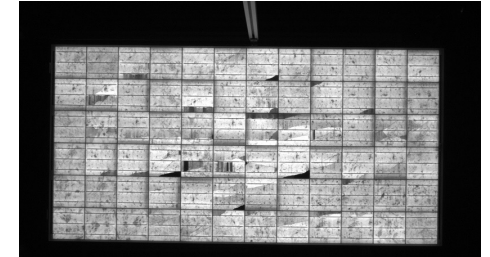
DuraMAT Webinar

April 11, 2022

# CONTENT

## PART 1

Automatic Defect Identification  
in Electroluminescence (EL)  
Images of Solar Modules



## PART 2

Field PV Data Mining Using  
PVPRO for Degradation  
Analysis

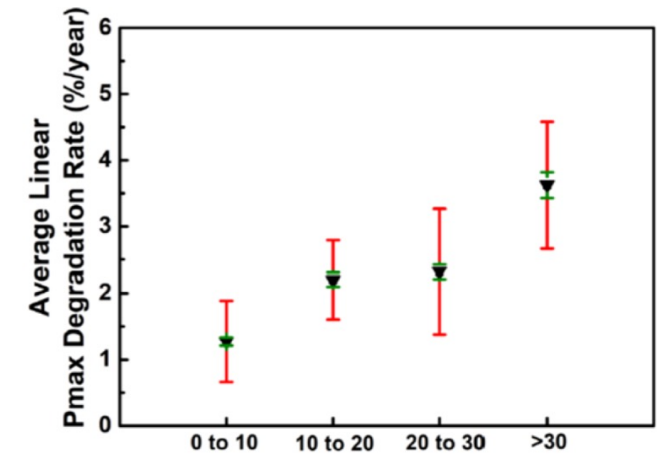


## OUTLINE:

- Automatic module transform and cell crop
- Automatic defect identification with deep learning
  - Analyze position distribution of defects on solar modules
- Automatic crack segmentation with deep learning
  - Predict worst-case degradation area based on crack patterns
  - Explain the mechanism underpinning the correlation between crack features and degradation (IV data)
- PV-Vision: Open-source package for EL image analysis of PV modules
  - <https://github.com/hackingmaterials/pv-vision>

- The power loss of solar modules is considered a threaten to the durability of the solar cells
- Cracks can propagate and lead to the electrical isolation and accelerate the degradation rate
- Other defects induced by fire, humidity, etc. can also cause power loss
- Electroluminescence imaging is used to inspect defects on solar modules

- How do cracks influence degradation?
- How to collect the features of the cracks from thousands or more solar modules?
- How to quickly determine whether the module in field needs to be replaced due to defects?
- Is there correlation between EL images and IV parameters (which determines degradation)?
- .....



(a)

Total no. of cracks

Relation of degradation rate and crack number[1]



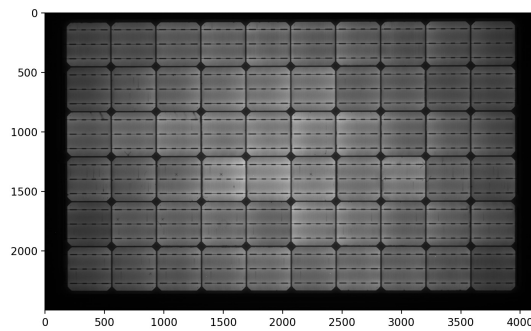
Electroluminescence image of solar module in lab

[1] N. Shiradkar, "Key Results from All India Survey of PV Module Reliability: 2016," in NREL PV Reliability Workshop, Lakewood, CO, 2018.

# Image preprocess

PART 1

EL Images Analysis



Raw image

Binary threshold

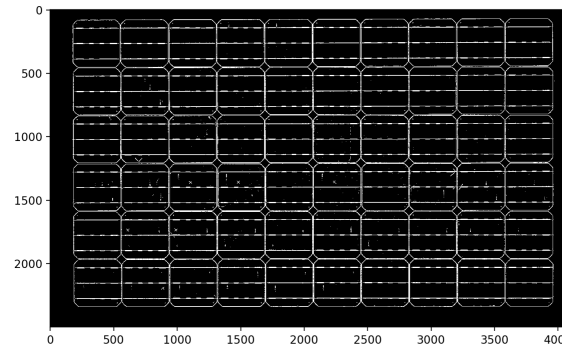
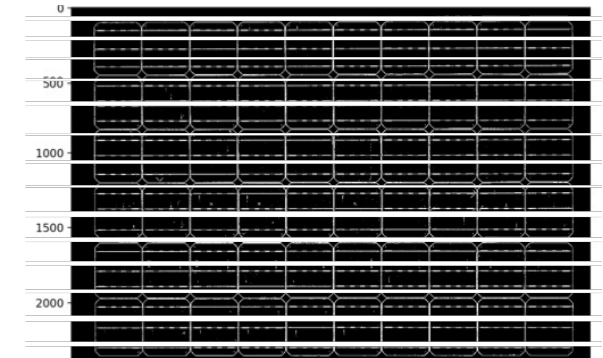


Image after binary threshold

Split along axis

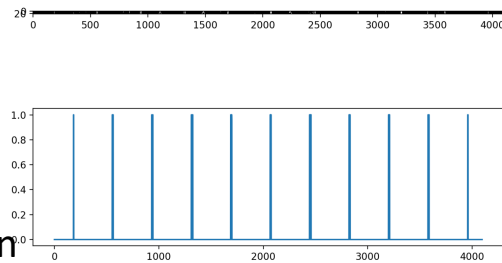


Schematic diagram of splits

Gray scale  
sum up

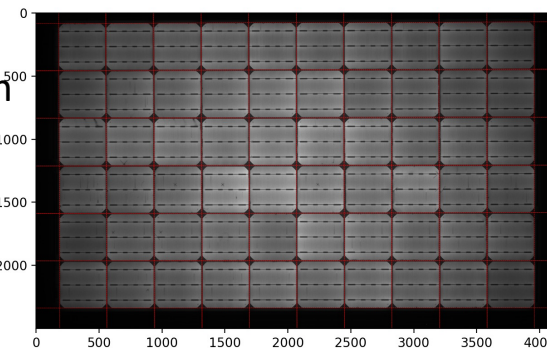


Detect edges in  
each split



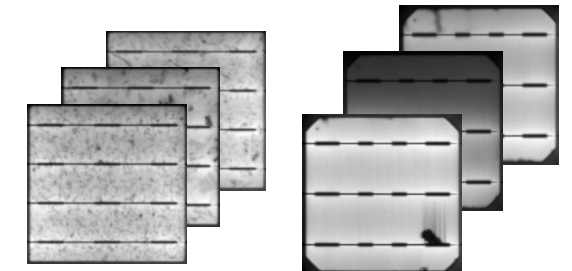
Detected internal  
edges from split

Linear fit  
edges in each  
split



Detected internal  
edges from module

Crop out

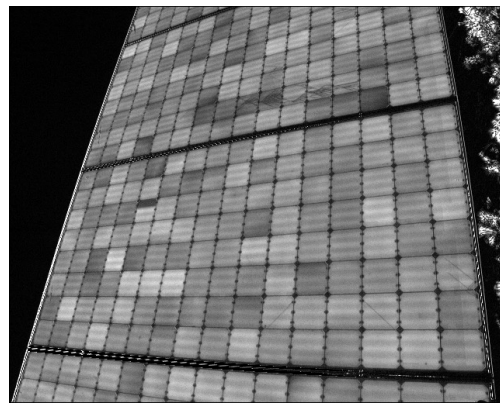


Around 30,000 single cells cropped out with  
~90% successful rate, excluding truncated(~3%)  
or poorly exposed(~10%) pictures

# Image preprocess

PART 1

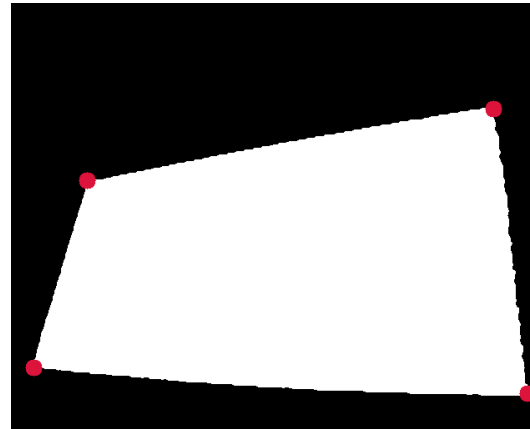
EL Images Analysis



Semantic segmentation

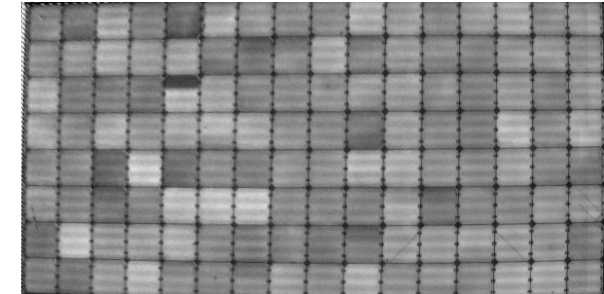


Corner detection



Mask with corner detection

Perspective transform



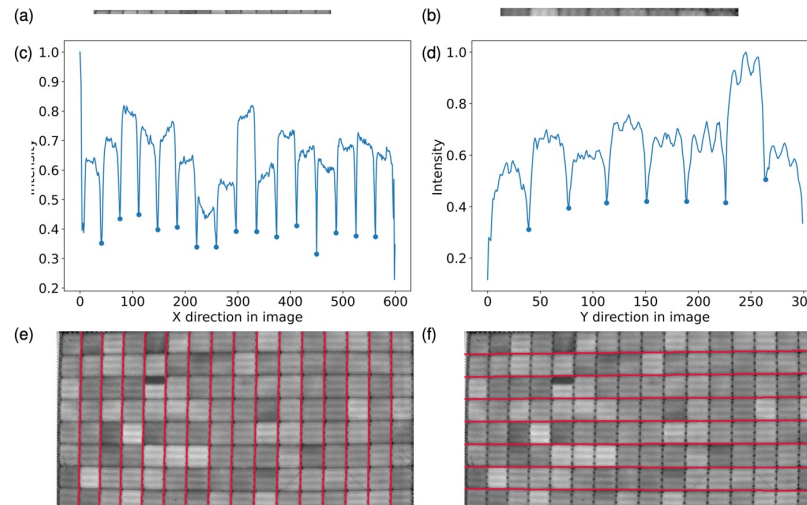
Transformed solar module

Raw image (field)

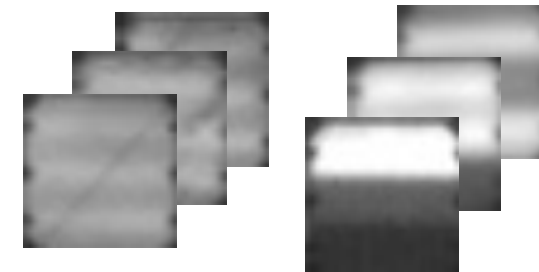
Gray scale sum up



Detect edges

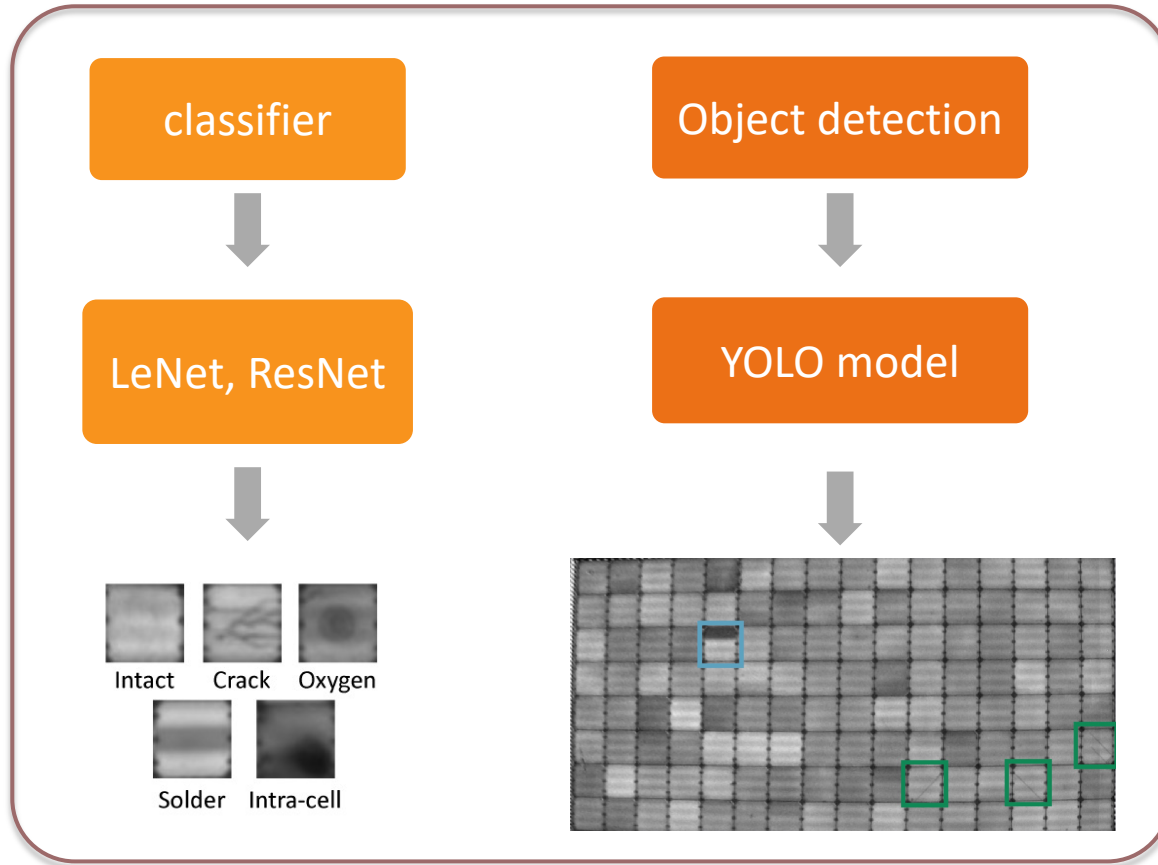


Crop out

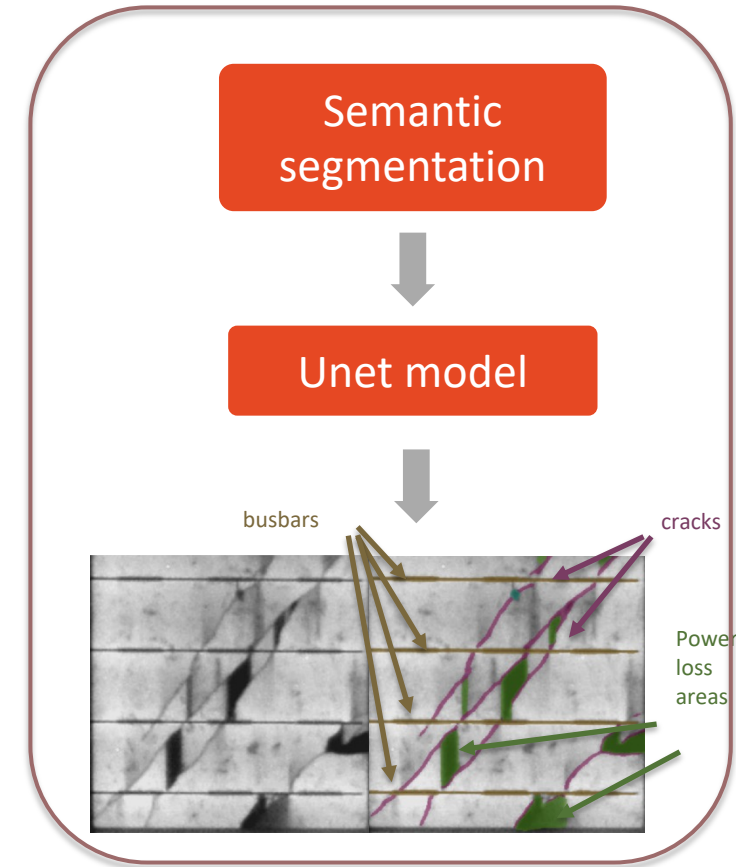


98.6% (18954/19228) modules successfully transformed

- Image analysis of EL images



Defect identification



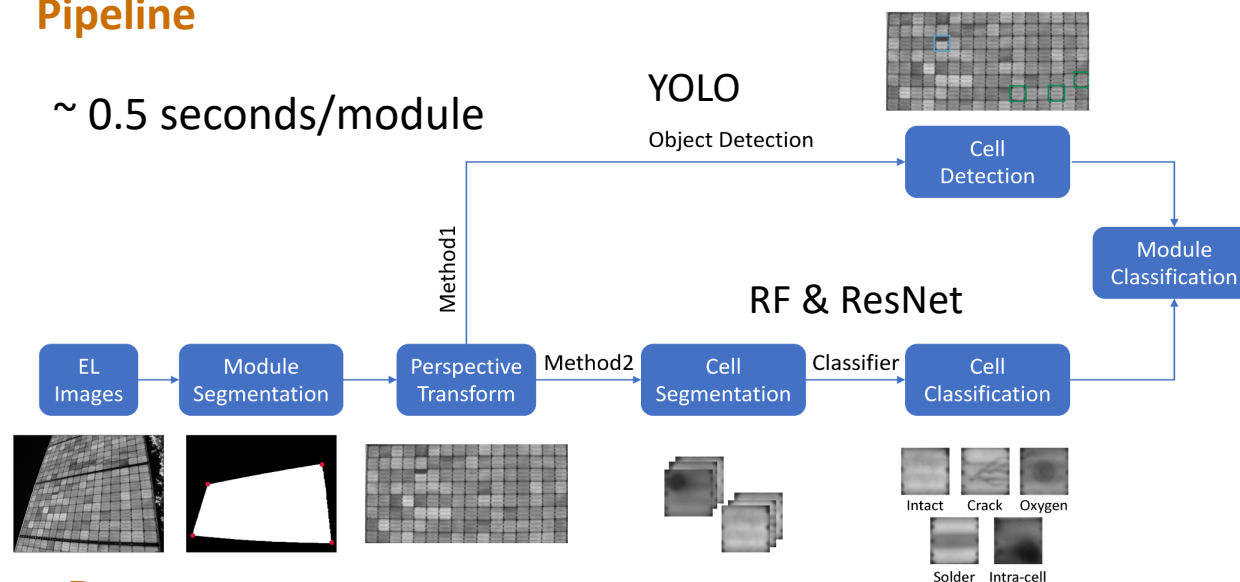
Crack segmentation

# Defect identification

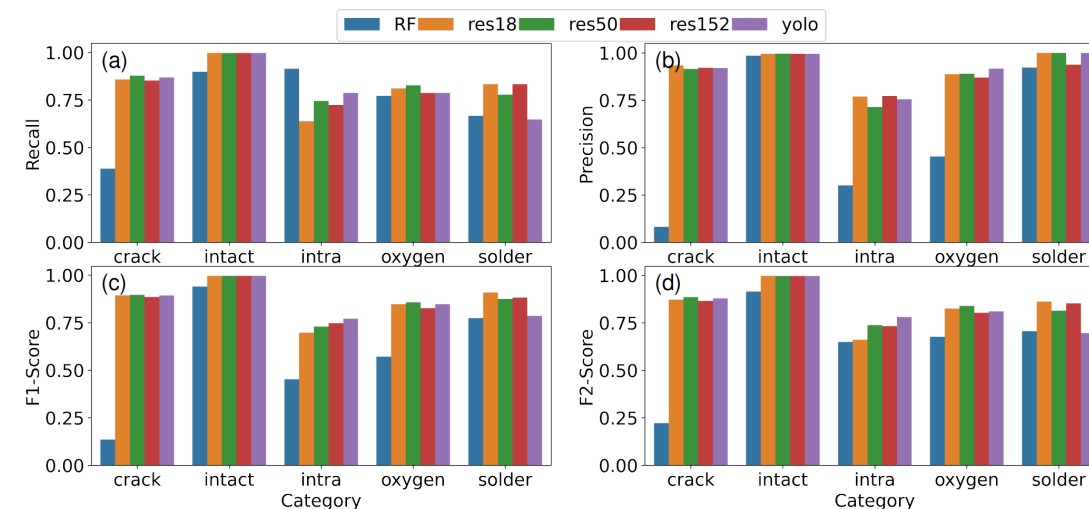
PART 1

EL Images Analysis

## Pipeline



## Evaluation



## Dataset

| Category    | Intact | Crack | Oxygen | Intra-cell | Solder |
|-------------|--------|-------|--------|------------|--------|
| Image       |        |       |        |            |        |
| Training    | 95048  | 1367  | 709    | 279        | 143    |
| 762 modules | 97.44% | 1.40% | 0.73%  | 0.29%      | 0.15%  |
| Validation  | 16618  | 345   | 127    | 47         | 18     |
| 134 modules | 96.87% | 2.01% | 0.74%  | 0.27%      | 0.10%  |
| Testing     | 16082  | 244   | 126    | 45         | 17     |
| 129 modules | 97.4%  | 1.48% | 0.76%  | 0.27%      | 0.10%  |

$$\text{Precision} = \frac{TP}{TP + FP}$$

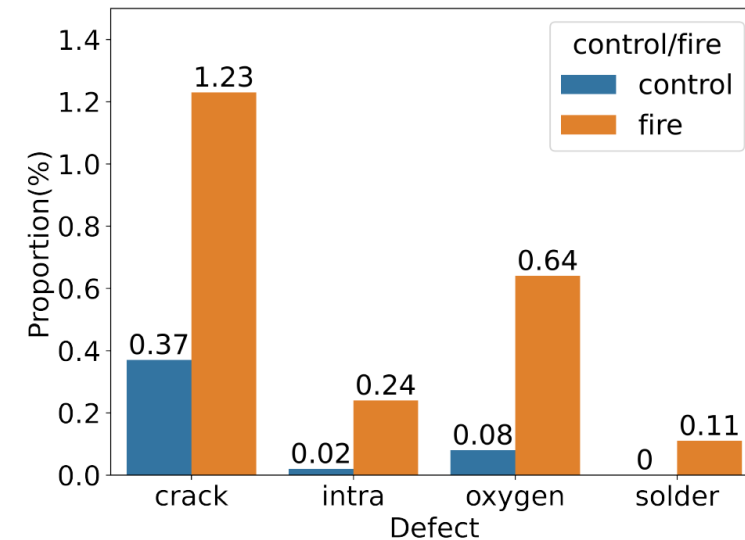
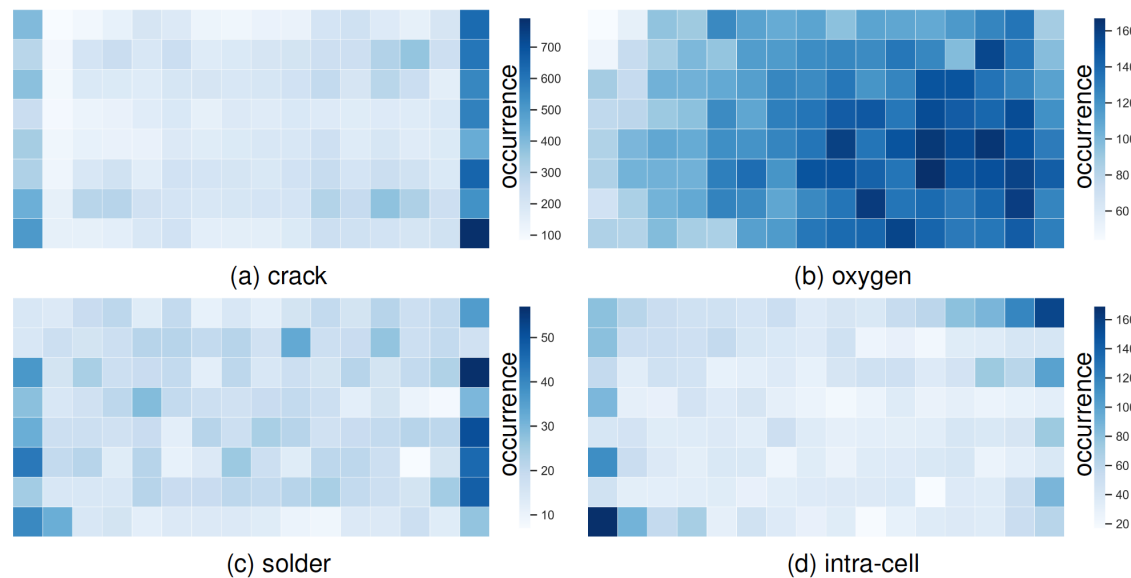
$$\text{Recall} = \frac{TP}{TP + FN}$$

$$F_1 = \frac{\sum 2TP}{\sum 2TP + FN + FP}$$

$$F_\beta = (1 + \beta^2) \frac{\text{Precision} * \text{Recall}}{\beta^2 * \text{Precision} + \text{Recall}}, \beta = 2 \text{ for } F_2$$

| Model         | YOLO | ResNet18 | ResNet50 | ResNet152  | RF   |
|---------------|------|----------|----------|------------|------|
| Avg F1 (val)  | 0.86 | 0.87     | 0.87     | 0.87       | 0.57 |
| Avg F1 (test) | 0.78 | 0.83     |          | Not tested |      |

## Position distribution

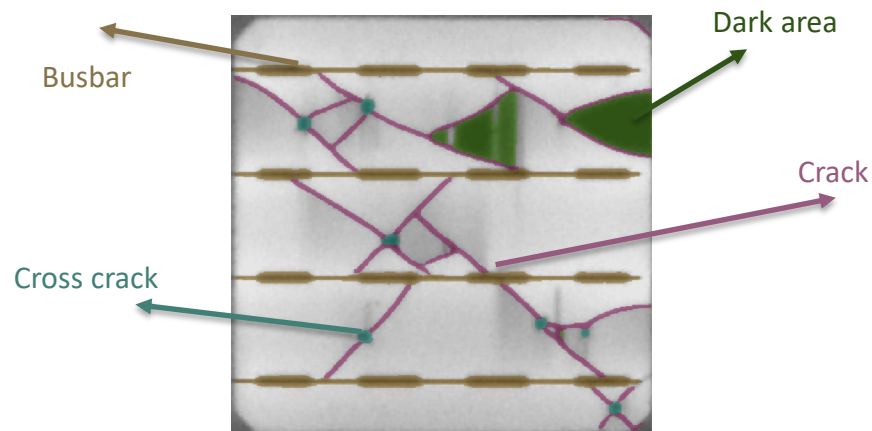


Distribution of defects on 18,825 PV modules affected by fire. Here each heatmap shows the quantity of defects observed in each cell in a 16x8 solar module. Defects are recognized by YOLO model. The right-hand side of the image is the side of the module closest to the ground during the EL survey.

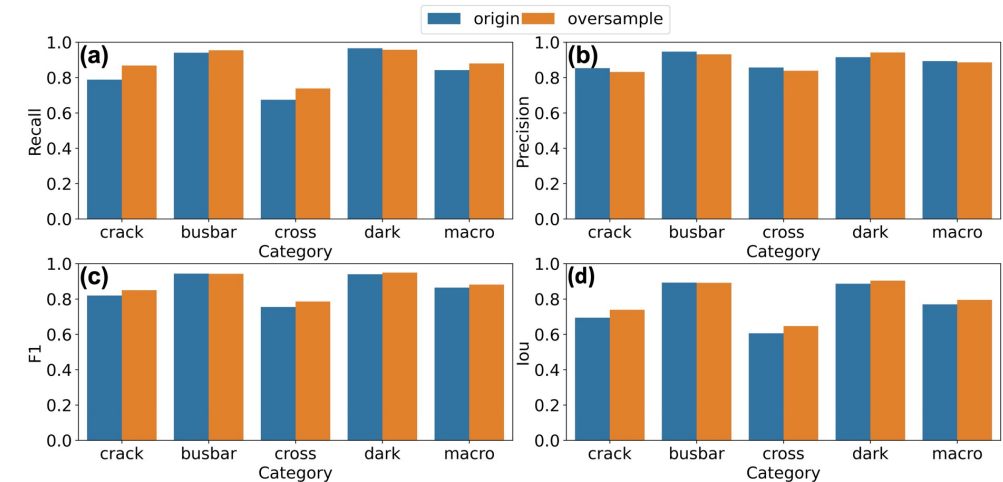
# Crack segmentation

## Dataset

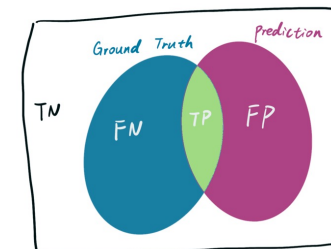
| Dataset          | Images | Crack | Busbar | Cross | Dark |
|------------------|--------|-------|--------|-------|------|
| Train            | 1272   | 493   | 1272   | 323   | 270  |
| Train oversample | 1765   | 986   | 1765   | 598   | 538  |
| Val              | 206    | 79    | 206    | 57    | 40   |
| Test             | 359    | 120   | 359    | 97    | 68   |
| Test crack       | 322    | 290   | 322    | 225   | 171  |



## Evaluation



| Dataset    | Avg Precision | Avg Recall | Avg F1 | Avg IoU |
|------------|---------------|------------|--------|---------|
| Val        | 0.886         | 0.879      | 0.882  | 0.795   |
| Test       | 0.883         | 0.867      | 0.875  | 0.782   |
| Test crack | 0.884         | 0.852      | 0.867  | 0.770   |



$$\text{Precision} = \frac{\sum_I \text{TP}}{\sum_I \text{TP} + \text{FP}}; \text{Recall} = \frac{\sum_I \text{TP}}{\sum_I \text{TP} + \text{FN}}$$

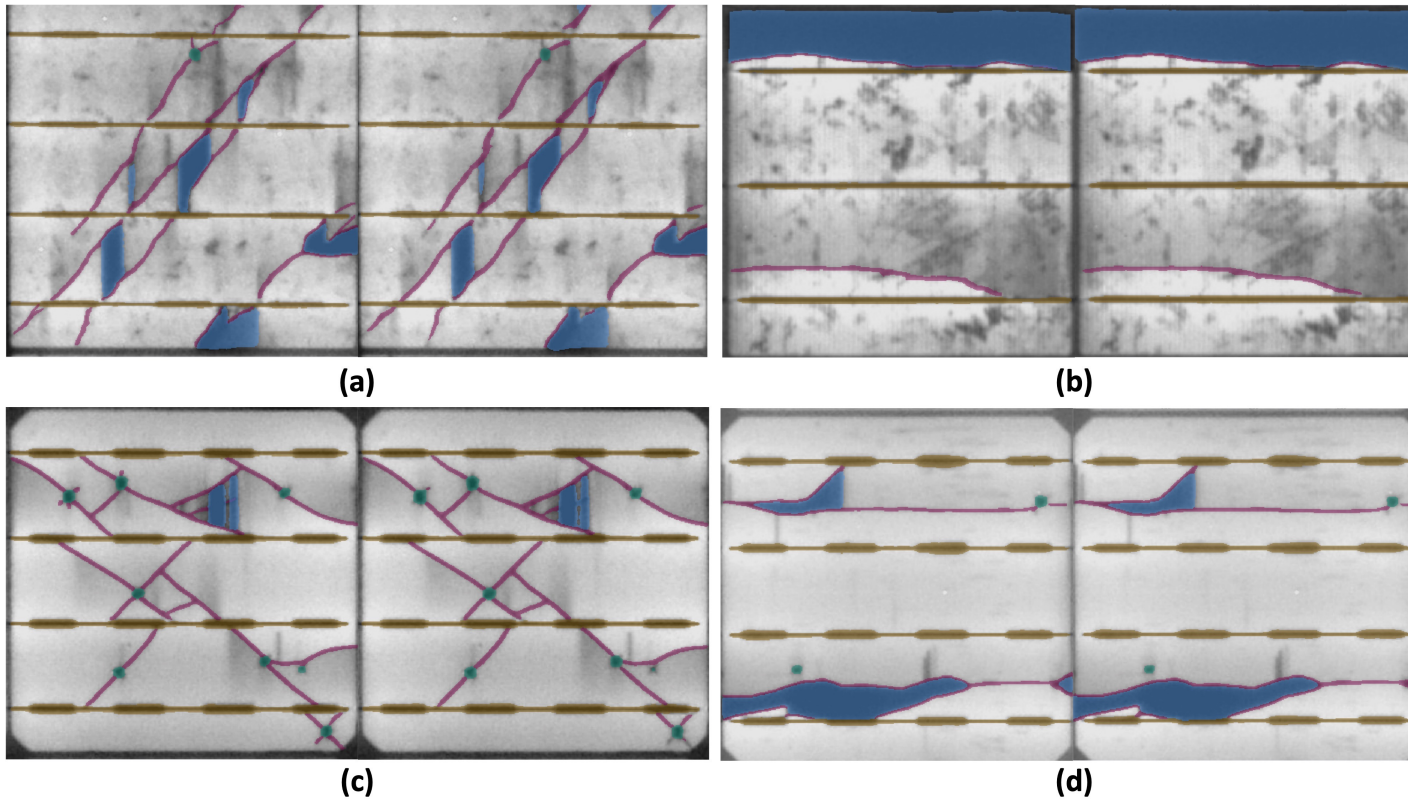
$$\text{F1} = \frac{\sum_I 2\text{TP}}{\sum_I 2\text{TP} + \text{FN} + \text{FP}}; \text{IoU} = \frac{\sum_I \text{TP}}{\sum_I \text{TP} + \text{FN} + \text{FP}}$$

# Crack segmentation

PART 1

EL Images Analysis

## Performance



Left: ground truth Right: prediction.

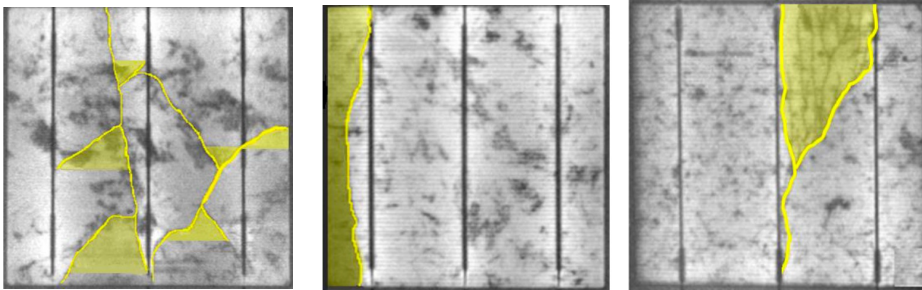
# Crack segmentation

PART 1

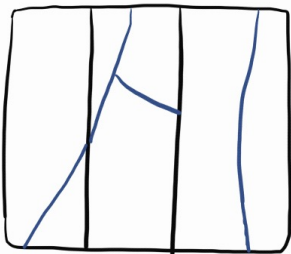
EL Images Analysis

## Inactive area prediction

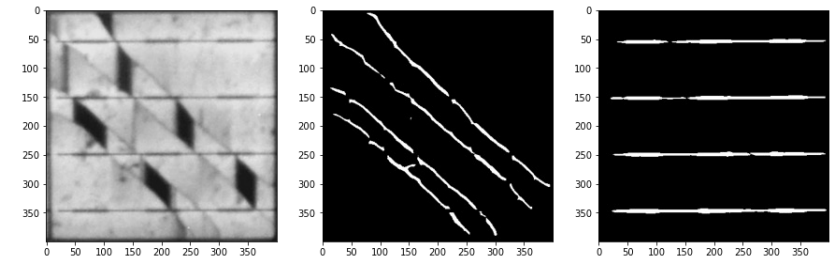
Worst case: isolated part becomes inactive [1]



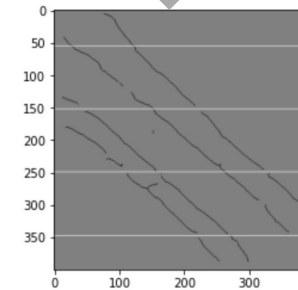
Algorithm: Horizontal diffusion of busbars



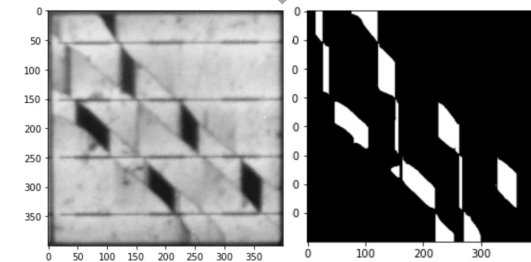
[1] MBJ, "MBJ Services - Solar Module Judgment Criteria EL," 2019.



Skeletonize

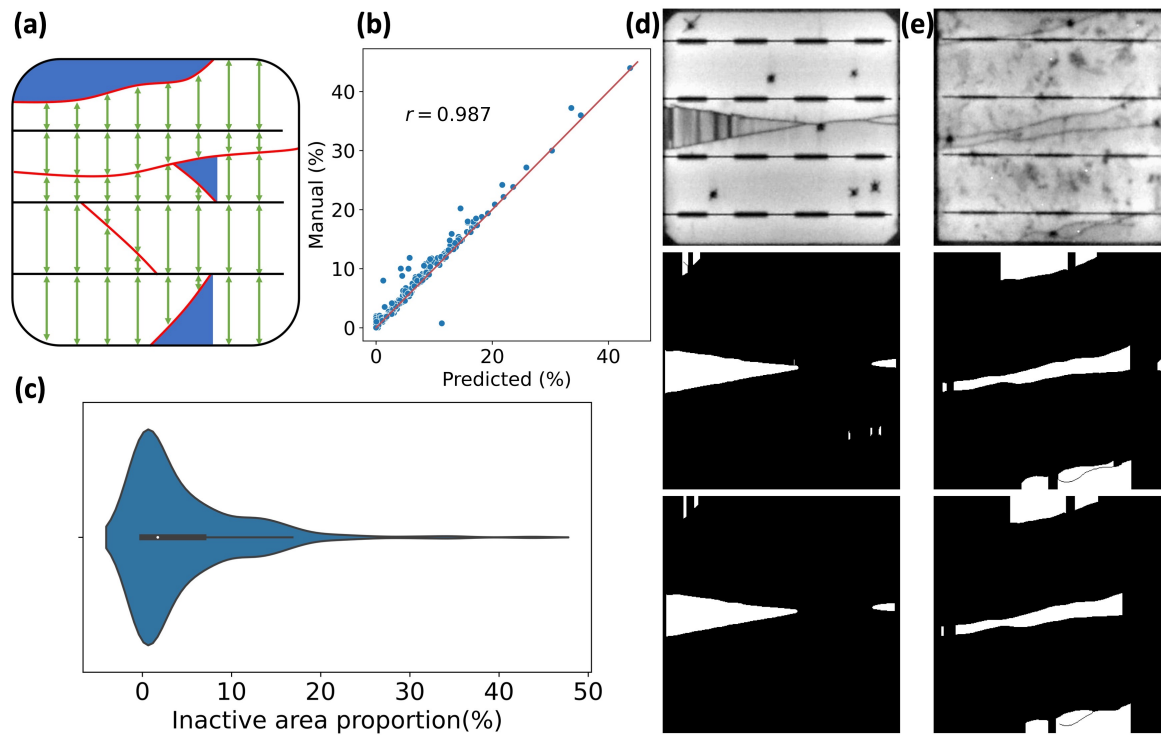


Busbar diffusion



Inactive area: 10.23%

## Result



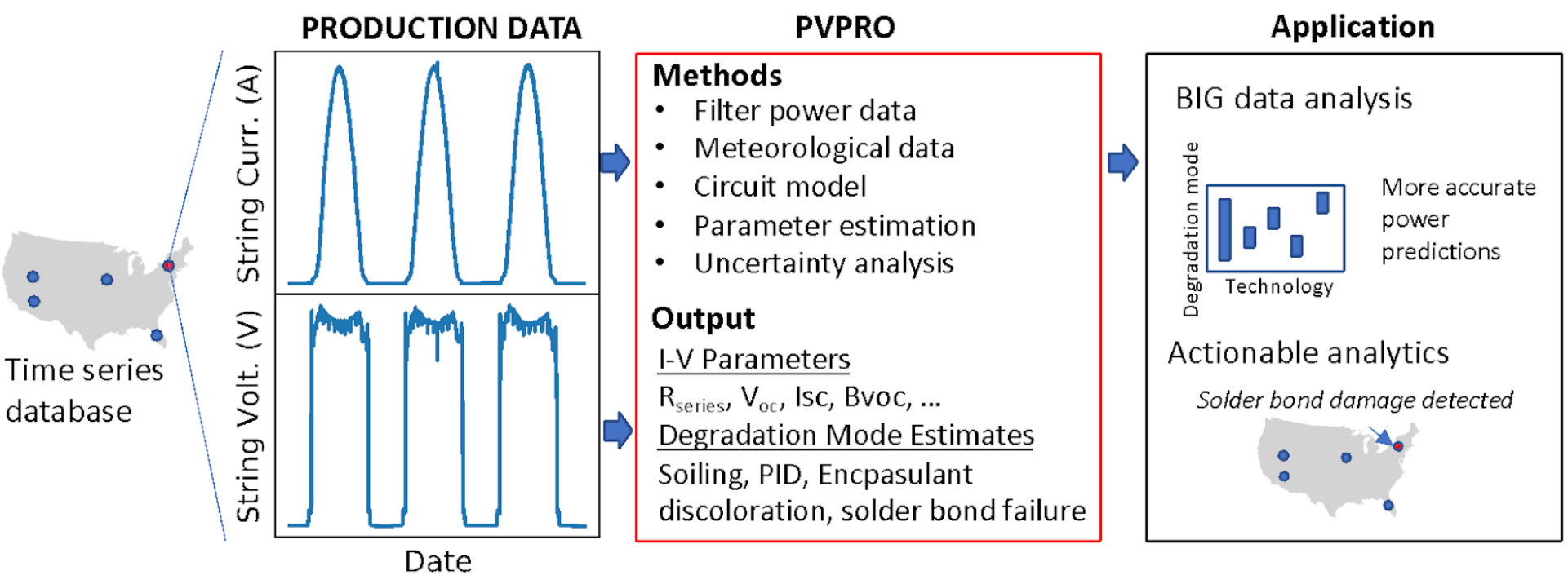
In the testing set:

- 75% of cells have inactive areas lower than 6.86%, and the average proportion is 4.54%.
- 31.4% of cells have zero inactive areas, which means they have insignificant cracks such as the one in the middle of figure (a).

- Explain the mechanism underpinning the correlation between crack features and degradation (IV data)
- Explore correlation between EL images and IV data
- Predict output power with EL images

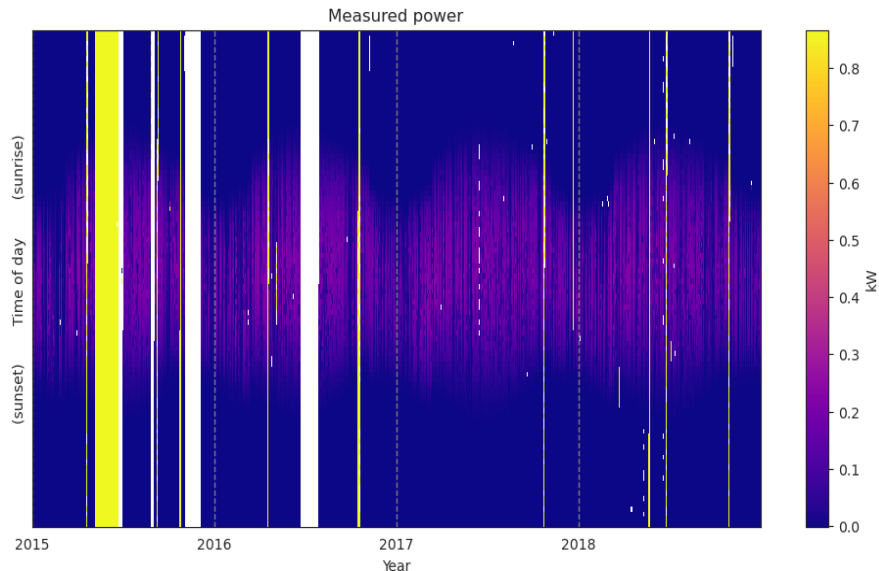
OUTLINE:

- Goal:** Use operation data (DC current, DC voltage, module temperature and plane-of-array irradiance) to determine time-evolution single-diode model parameters of PV modules.



# Methods – Data Cleaning

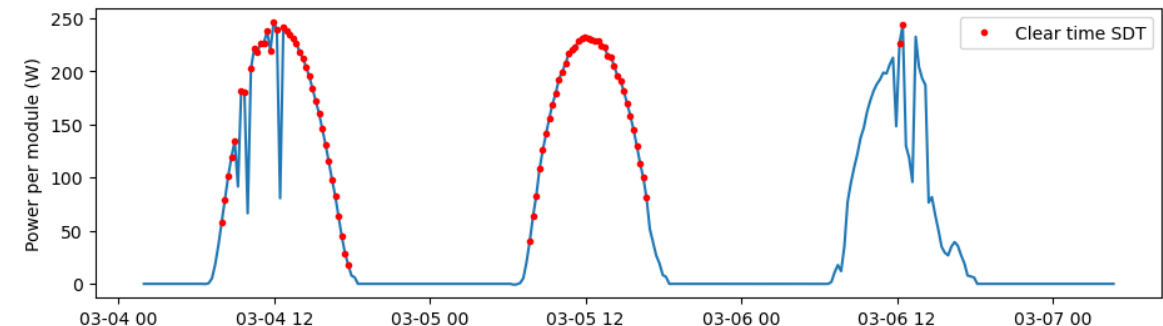
## Basic Quality Checks



- **First inspect data and fix issues!**
- Use solar data tools for basic quality checks:
  - Time shifts.
  - Capacity changes.
  - Data completeness
  - Bad data detection.
  - Visualization.

## Clear time detection

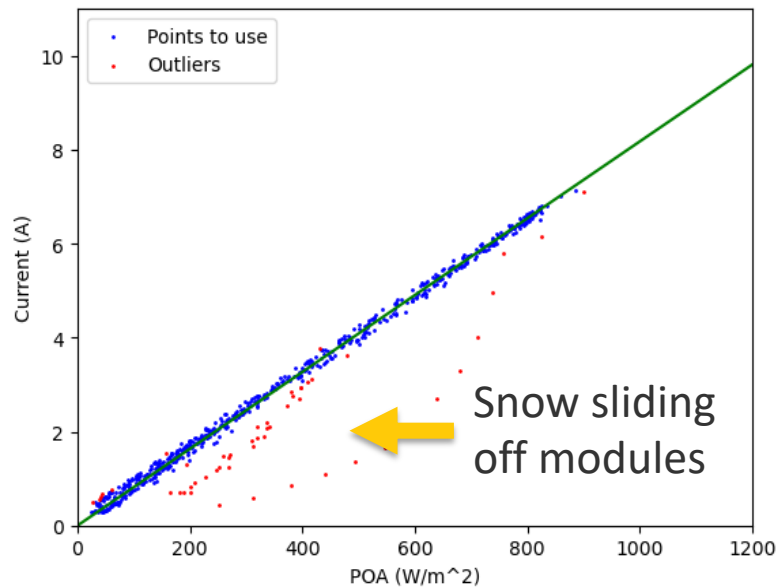
- Developed data-centric clear time filter (Solar data tools).
- Clear if:
  - Power is close to clear sky model and
  - Second-order difference is close to second-order difference for clear sky model.



# Methods – Data Cleaning

## Current irradiance filter

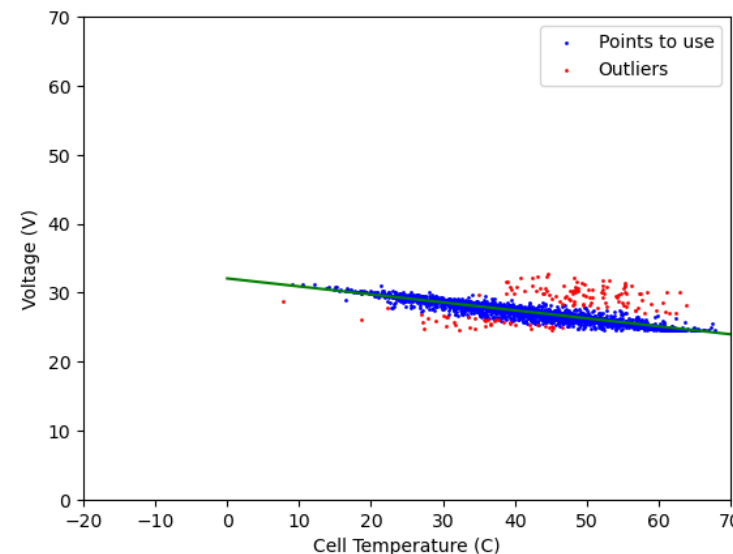
- Current at MPP is expected to be proportional to plane-of-array (POA) irradiance.



- Method:** Use Huber regressor (scikit-learn) to perform a linear fit between current and irradiance, classifying points as **points to use** or **outliers**.

## Temperature voltage filter

- Maximum power voltage and temperature should be linearly related.

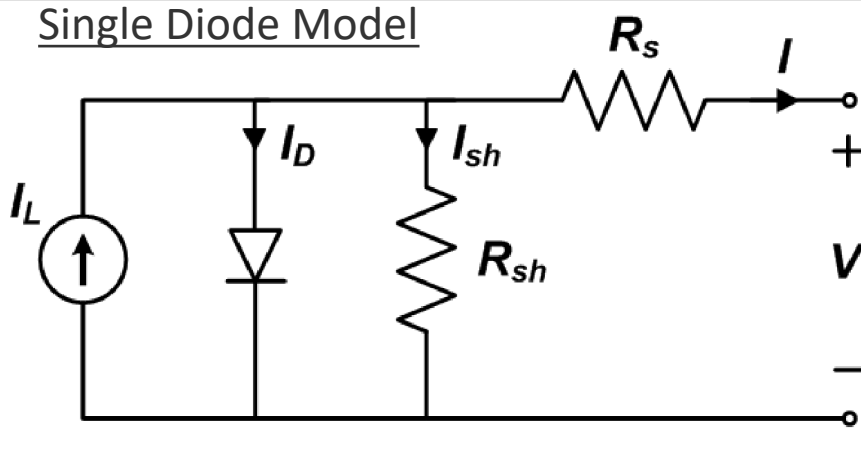


- Deviations can occur if:
  - MPP tracking errors.
  - MPP tracking window limits.

- Method:** Use Huber regressor to perform a linear fit between voltage and temperature, classifying points as **points to use** or **outliers**.
- (Only classify as outliers if POA > 200 W/m<sup>2</sup>)

# Methods – Maximum Power Point Fitting

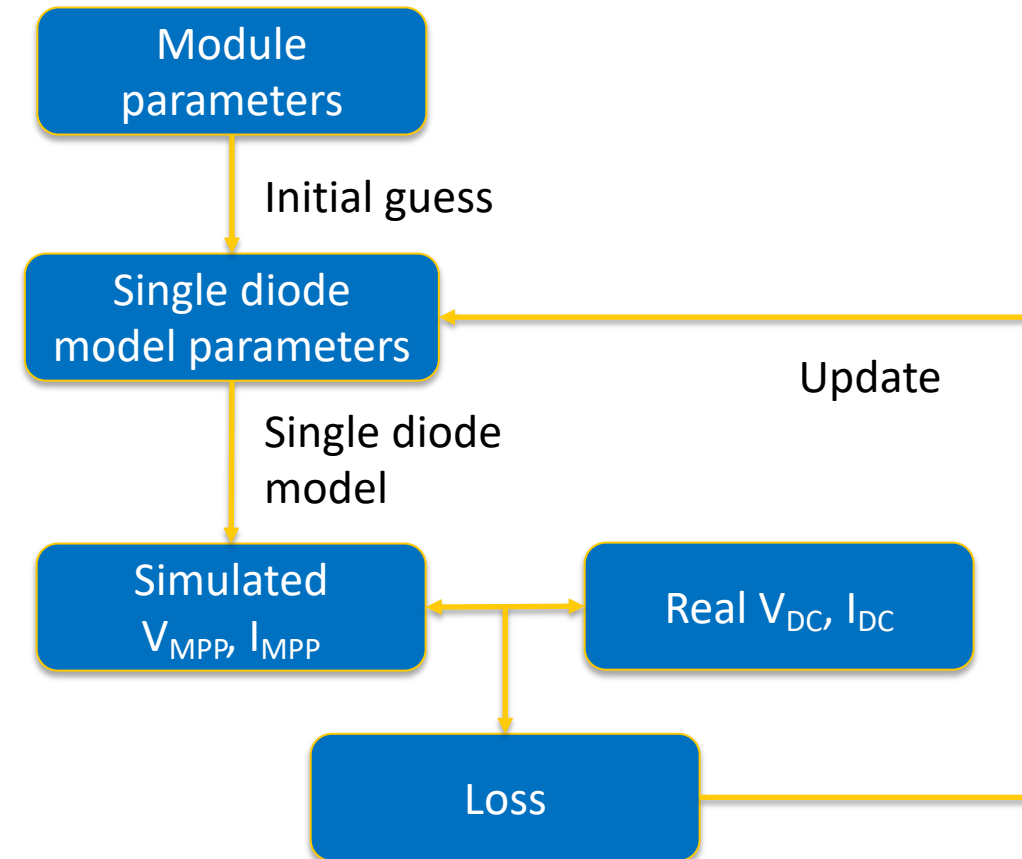
Single Diode Model



$$I = I_L - I_0 \left[ \exp \left( \frac{V + IR_s}{nV_{th}} \right) - 1 \right] - \frac{V + IR_s}{R_{sh}}$$

PVPRO uses 5 fit parameters:

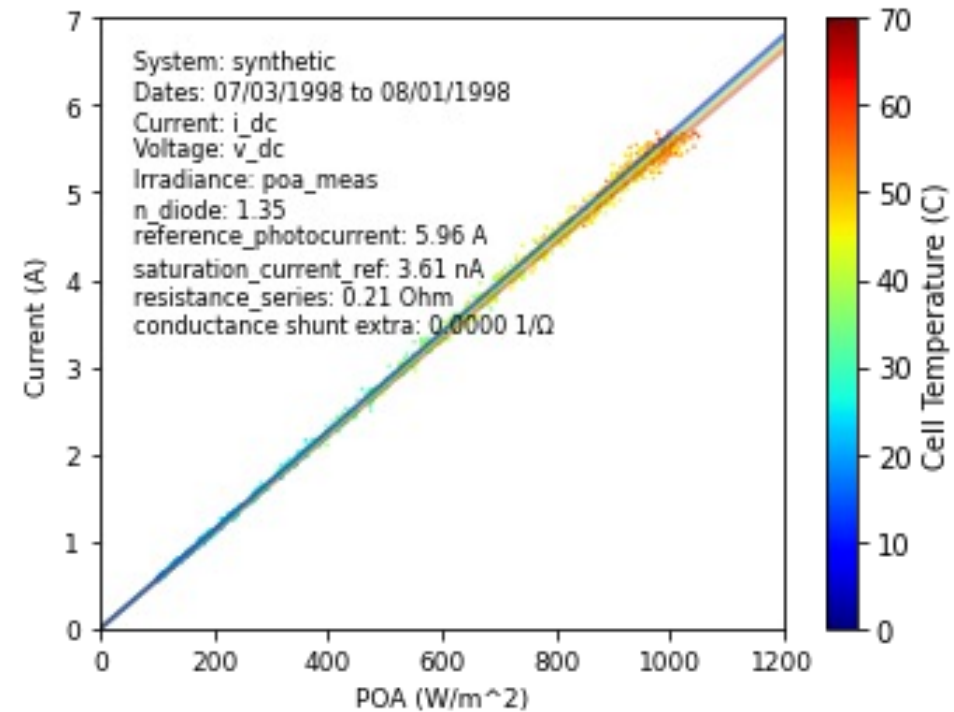
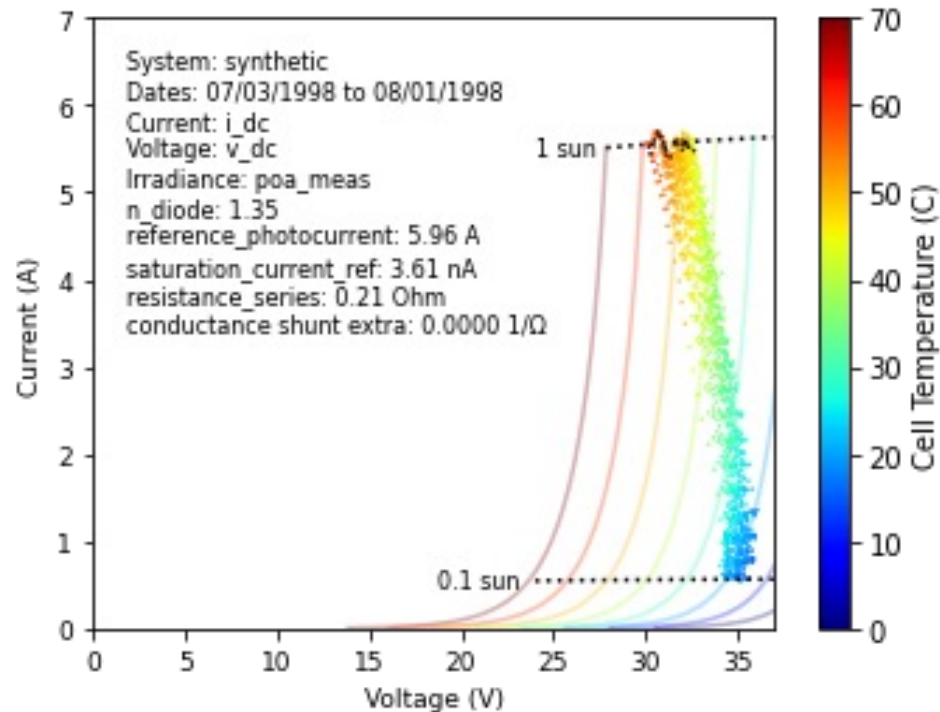
- Saturation current at reference conditions ( $I_0$ )
- Photocurrent at reference conditions ( $I_L$ )
- Series resistance ( $R_s$ )
- Extra shunt resistance ( $R_{sh}$ )
- Diode factor ( $n$ )



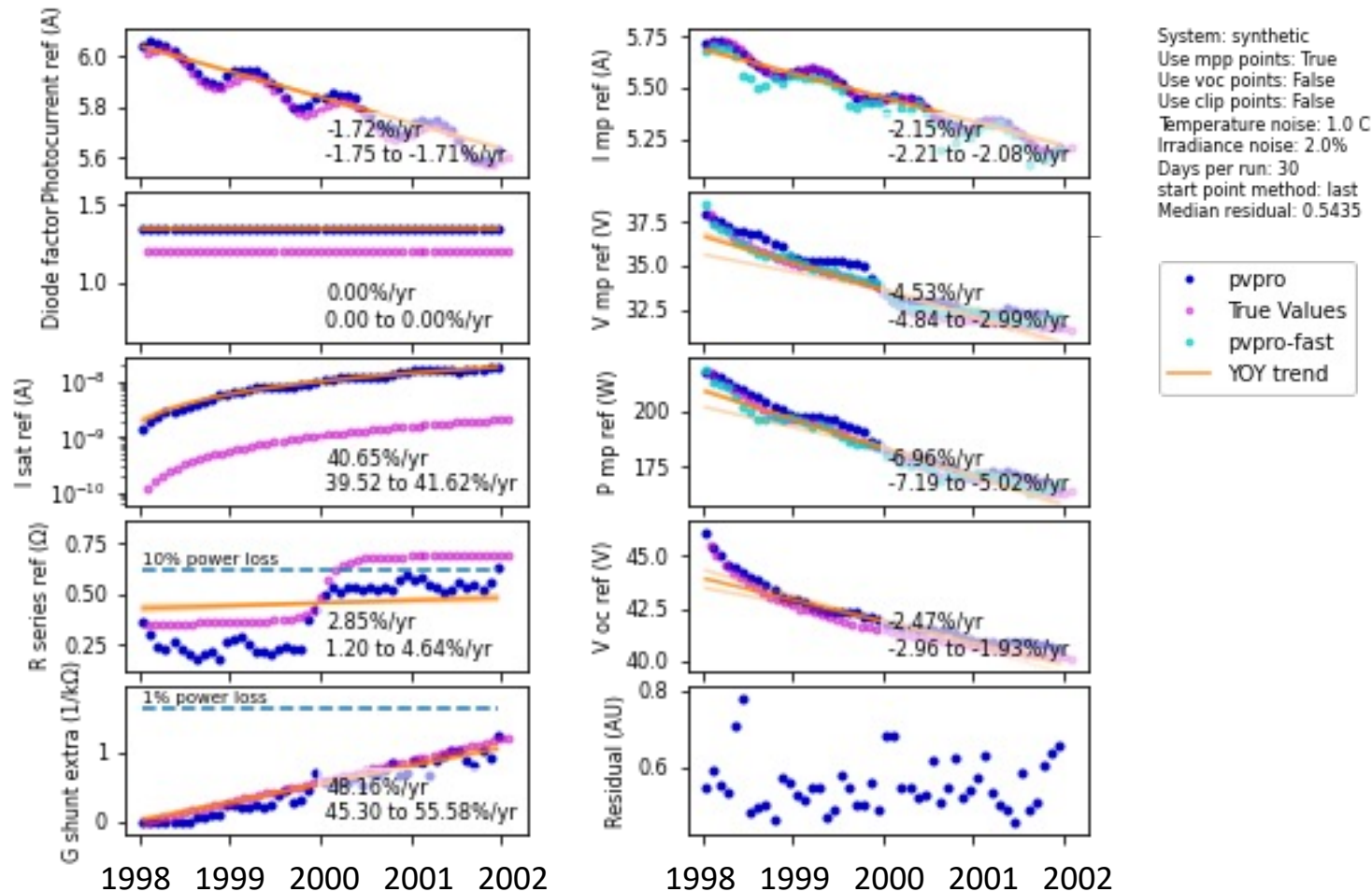
# Application: Synthetic data

## Data:

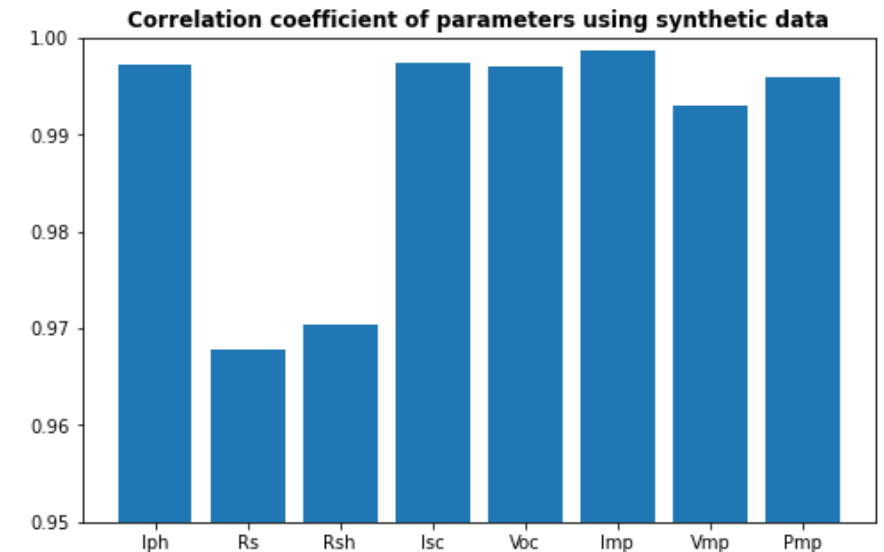
Simulate PV system over time with various parameter degradation using NSRDB weather data (<https://nsrdb.nrel.gov/>)  
Irradiance sensor has multiplicative 2% error, temperature sensor has additive 1 C error, 15-minute data.



# Application: Synthetic data



## Correlation coefficient of parameters



Mean correlation coefficient = 0.99

# Field data (NIST)



## ■ Ground dataset

- 1152 modules
- 271 kW



## ■ Canopy dataset

- 1032 modules
- 243 kW



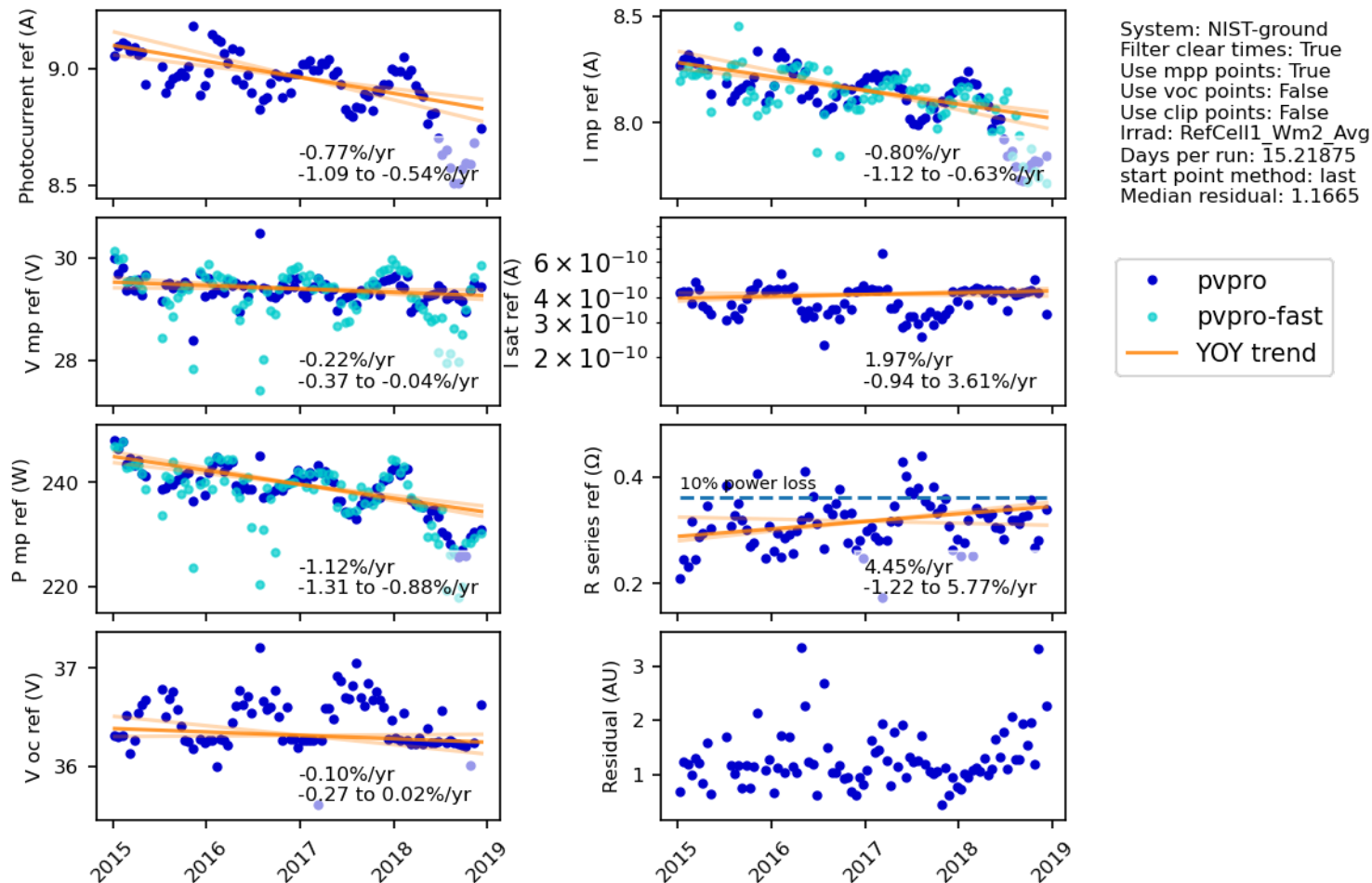
## ■ Roof dataset

- 132 modules
- 73.3 kW



<https://pvdata.nist.gov/>

# Results: Field data



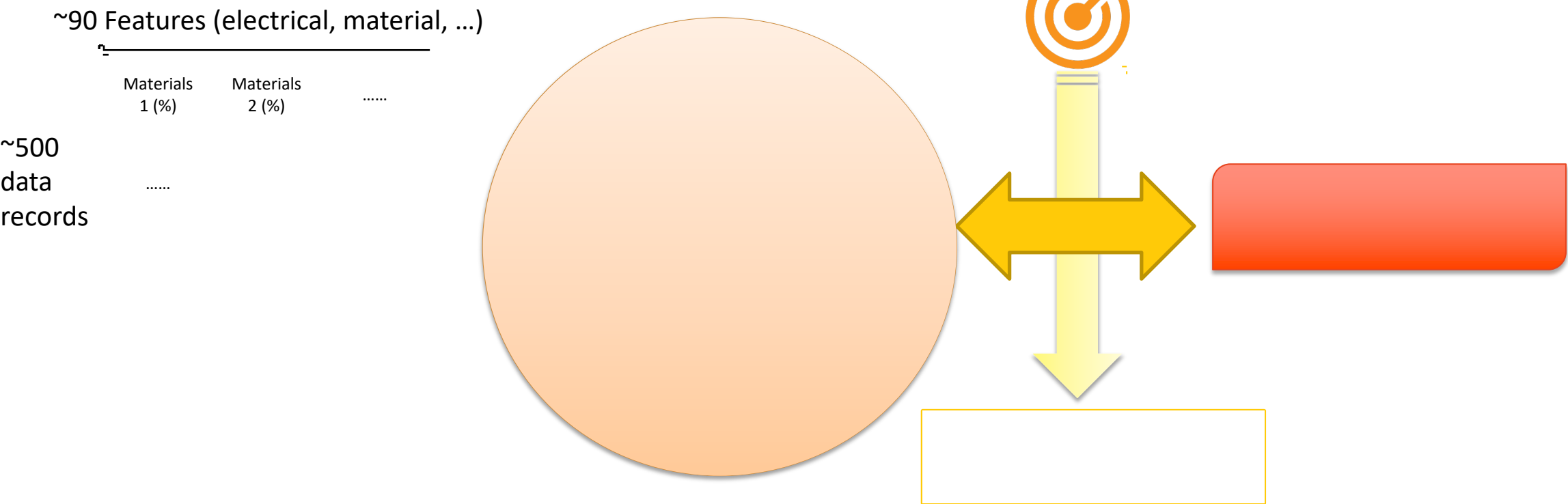
- Reasonable and **clear seasonality trend** observed
- Degradation rates** can be extracted for the SDM parameters

## Ongoing:

- Get the **ground truth** (from indoor flashing test / reference module)
- Correlate the **data quality** with the variation of results

# Ongoing: Connecting BOM with degradation

## Bill of material files from PVEL



# Summary

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## Conclusions:

- PVPRO provides an **automatic pipeline** including data cleaning, filtering, feature extraction and analysis.
- **Degradation patterns** of model parameters can be extracted by PVPRO using operation data
- Continued code development and tutorials on <https://github.com/DuraMAT/pvpro>

## Future work:

- Determine **off-maximum power point** with PVPRO
- Refine the application of PVPRO on more **large-scale PV systems** and investigate the degradation

PV vision



PVPRO



# Q&A and thank you!

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**PVPRO:** T. Karin\*, X. Chen, B. Li, A. Jain, C. Hansen, M. Deceglie, B. Meyers, L. Schelhas, B. King, D. Jordan, S. Moffitt

**PV-Vision:** X. Chen\*, T. Karin, A. Jain, C. Libby, R. Sundaramoorthy, M. Deceglie, T. Silverman, N. Bosco, M. Owen-Bellini, E. Young, X. He, E. Bernhardt, P. Hacke, M. Bolen, D. Fregosi, W. Hobbs, PVEL company

DuraMAT Webinar

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